YouTube video links for this project are as follows:

1) Dynamixel Servo Control: <https://www.youtube.com/watch?v=NHNJTO2-MgY>

2) HR-OS5 Arm motion Control: <https://www.youtube.com/watch?v=WE-tsQba5b0>

* Due to various difficulties faced which are mentioned in the report, we were only able to control one arm of the robot.
* But now, since we know the process to be followed to control the robot motions, we can create some nice motions using the HR-OS5 in the Spring term.